Computergestuetzte Mathematik (Lineare Algebra mit Maple)

Lektion 7 (3. Dez.)

Vektoren und Matrizen

```
> x := <1,2,3>;
```

$$x := \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad (1.1)$$

```
> y := <4|5|6>;
```

$$y := \begin{bmatrix} 4 & 5 & 6 \end{bmatrix} \quad (1.2)$$

```
> A := << 1 | 2 | 3 >,
        < 4 | 5 | 6 >,
        < 7 | 8 | 9 >>;
```

$$A := \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \quad (1.3)$$

```
> about(A);
Matrix(3, 3, [[1,2,3],[4,5,6],[7,8,9]]):
  property aliased to Matrix(3, 3, [[1,2,3],[4,5,6],[7,8,9]])
```

```
> about(x);
Vector(3, [1,2,3]):
  property aliased to Vector(3, [1,2,3])
```

```
> AA := Matrix(3, 3, [[1, 2, 3], [4, 5, 6], [7, 8, 9]]); #
  alternative Eingabe
```

$$AA := \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \quad (1.4)$$

```
> xx := Vector(3,[1,2,3]);
```

(1.5)

$$xx := \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \tag{1.5}$$

```
> A*x;
```

Error, (in rtable/Product) invalid arguments

```
> A . x;
```

$$\begin{bmatrix} 14 \\ 32 \\ 50 \end{bmatrix} \tag{1.6}$$

```
> B := < < 1, 4, 7 > | < 2, 5, 8 > | < 3 , 6 , 9 >>;
```

$$B := \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \tag{1.7}$$

```
> A - B;
```

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \tag{1.8}$$

```
> A *~ B;
```

$$\begin{bmatrix} 1 & 4 & 9 \\ 16 & 25 & 36 \\ 49 & 64 & 81 \end{bmatrix} \tag{1.9}$$

```
> A^2;
```

$$\begin{bmatrix} 30 & 36 & 42 \\ 66 & 81 & 96 \\ 102 & 126 & 150 \end{bmatrix} \tag{1.10}$$

```
> < A | B >;
```

$$\begin{bmatrix} 1 & 2 & 3 & 1 & 2 & 3 \\ 4 & 5 & 6 & 4 & 5 & 6 \\ 7 & 8 & 9 & 7 & 8 & 9 \end{bmatrix} \tag{1.11}$$

```
> < A , B >;
```

(1.12)

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \\ 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \tag{1.12}$$

```
> Id := A^0; #Achtung
```

$$Id := 1 \tag{1.13}$$

```
> about(Id);
```

```
1:
  All numeric values are properties as well as objects.
  Their location in the property lattice is obvious,
  in this case integer.
```

```
> C := A + 1;
```

$$C := \begin{bmatrix} 2 & 2 & 3 \\ 4 & 6 & 6 \\ 7 & 8 & 10 \end{bmatrix} \tag{1.14}$$

```
> C^(-1);
```

$$\begin{bmatrix} -6 & -2 & 3 \\ -1 & \frac{1}{2} & 0 \\ 5 & 1 & -2 \end{bmatrix} \tag{1.15}$$

```
> % . (A + 1);
```

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \tag{1.16}$$

```
> (A + 1) . (1.15);
```

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \tag{1.17}$$

```
> Matrix(3, shape = identity);
```

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \tag{1.18}$$

```
> Matrix( <1,2,3>, shape = diagonal);
```

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \tag{1.19}$$

```
> circ := Matrix(4, (i,j) -> (i-j)^3);
```

$$circ := \begin{bmatrix} 0 & -1 & -8 & -27 \\ 1 & 0 & -1 & -8 \\ 8 & 1 & 0 & -1 \\ 27 & 8 & 1 & 0 \end{bmatrix} \tag{1.20}$$

```
> circ^(-1);
```

$$\begin{bmatrix} 0 & -\frac{1}{36} & \frac{2}{9} & -\frac{1}{36} \\ \frac{1}{36} & 0 & -\frac{3}{4} & \frac{2}{9} \\ -\frac{2}{9} & \frac{3}{4} & 0 & -\frac{1}{36} \\ \frac{1}{36} & -\frac{2}{9} & \frac{1}{36} & 0 \end{bmatrix} \tag{1.21}$$

```
> hilbert := Matrix(4, (i,j) -> 1/(i+j-1));
```

$$hilbert := \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} \\ \frac{1}{4} & \frac{1}{5} & \frac{1}{6} & \frac{1}{7} \end{bmatrix} \tag{1.22}$$

```
> with(LinearAlgebra);
```

[*&x*, *Add*, *Adjoint*, *BackwardSubstitute*, *BandMatrix*, *Basis*, *BezoutMatrix*, *BidiagonalForm*, *BilinearForm*, *CARE*, *CharacteristicMatrix*, *CharacteristicPolynomial*, *Column*, *ColumnDimension*, *ColumnOperation*, *ColumnSpace*, *CompanionMatrix*, *CompressedSparseForm*, *ConditionNumber*, *ConstantMatrix*, *ConstantVector*, *Copy*, *CreatePermutation*, *CrossProduct*, *DARE*, *DeleteColumn*, *DeleteRow*, *Determinant*, *Diagonal*, *DiagonalMatrix*, *Dimension*, *Dimensions*, *DotProduct*, *EigenConditionNumbers*, (1.23)

Eigenvalues, *Eigenvectors*, *Equal*, *ForwardSubstitute*, *FrobeniusForm*, *FromCompressedSparseForm*, *FromSplitForm*, *GaussianElimination*, *GenerateEquations*, *GenerateMatrix*, *Generic*, *GetResultDataType*, *GetResultShape*, *GivensRotationMatrix*, *GramSchmidt*, *HankelMatrix*, *HermiteForm*, *HermitianTranspose*, *HessenbergForm*, *HilbertMatrix*, *HouseholderMatrix*, *IdentityMatrix*, *IntersectionBasis*, *IsDefinite*, *IsOrthogonal*, *IsSimilar*, *IsUnitary*, *JordanBlockMatrix*, *JordanForm*, *KroneckerProduct*, *LA_Main*, *LUDecomposition*, *LeastSquares*, *LinearSolve*, *LyapunovSolve*, *Map*, *Map2*, *MatrixAdd*, *MatrixExponential*, *MatrixFunction*, *MatrixInverse*, *MatrixMatrixMultiply*, *MatrixNorm*, *MatrixPower*, *MatrixScalarMultiply*, *MatrixVectorMultiply*, *MinimalPolynomial*, *Minor*, *Modular*, *Multiply*, *NoUserValue*, *Norm*, *Normalize*, *NullSpace*, *OuterProductMatrix*, *Permanent*, *Pivot*, *PopovForm*, *ProjectionMatrix*, *QRDecomposition*, *RandomMatrix*, *RandomVector*, *Rank*, *RationalCanonicalForm*, *ReducedRowEchelonForm*, *Row*, *RowDimension*, *RowOperation*, *RowSpace*, *ScalarMatrix*, *ScalarMultiply*, *ScalarVector*, *SchurForm*, *SingularValues*, *SmithForm*, *SplitForm*, *StronglyConnectedBlocks*, *SubMatrix*, *SubVector*, *SumBasis*, *SylvesterMatrix*, *SylvesterSolve*, *ToeplitzMatrix*, *Trace*, *Transpose*, *TridiagonalForm*, *UnitVector*, *VandermondeMatrix*, *VectorAdd*, *VectorAngle*, *VectorMatrixMultiply*, *VectorNorm*, *VectorScalarMultiply*, *ZeroMatrix*, *ZeroVector*, *Zip*]

```
> Transpose(A);
```

$$\begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} \tag{1.24}$$

```
> B := A;
```

$$B := \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \tag{1.25}$$

```
> B[1,2] := 222;
```

$$B_{1,2} := 222 \tag{1.26}$$

```
> B;
```

$$\begin{bmatrix} 1 & 222 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \tag{1.27}$$

```
> A;
```

$$\begin{bmatrix} 1 & 222 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \quad (1.28)$$

```
> A[1,2] := 2;
```

$$A_{1,2} := 2 \quad (1.29)$$

```
> B := Copy(A);
```

$$B := \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \quad (1.30)$$

```
> B[1,2] := 777;
```

$$B_{1,2} := 777 \quad (1.31)$$

```
> B;
```

$$\begin{bmatrix} 1 & 777 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \quad (1.32)$$

```
> A;
```

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \quad (1.33)$$

Lineare Gleichungssysteme

```
> restart:
> g1 := x + y - z = 1;
```

$$g1 := x + y - z = 1 \quad (2.1)$$

```
> g2 := 2*x + y - 3*z = 0;
```

$$g2 := 2x + y - 3z = 0 \quad (2.2)$$

```
> g3 := x - 2*z = -1;
```

$$g3 := x - 2z = -1 \quad (2.3)$$

```
> solve({g1, g2, g3}, {x,y,z});
```

$$\{x = -1 + 2z, y = 2 - z, z = z\} \quad (2.4)$$

```
> subs(%, {g1, g2 , g3});
```

$$\{-1 = -1, 0 = 0, 1 = 1\} \quad (2.5)$$

```
> with(LinearAlgebra):
> B := GenerateMatrix( [g1, g2, g3], [x, y, z], augmented = true)
```

```
;
```

$$B := \begin{bmatrix} 1 & 1 & -1 & 1 \\ 2 & 1 & -3 & 0 \\ 1 & 0 & -2 & -1 \end{bmatrix} \quad (2.6)$$

```
> A := SubMatrix(B, 1..3, 1..3);
```

$$A := \begin{bmatrix} 1 & 1 & -1 \\ 2 & 1 & -3 \\ 1 & 0 & -2 \end{bmatrix} \quad (2.7)$$

```
> SubMatrix(B, 1..3, 4..4);
```

$$\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \quad (2.8)$$

```
> whattype(%);
```

$$\mathit{Matrix} \quad (2.9)$$

```
> b := convert((2.8), Vector);
```

$$b := \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \quad (2.10)$$

```
> whattype(%);
```

$$\mathit{Vector}_{column} \quad (2.11)$$

```
> x := LinearSolve(A, b);
```

$$x := \begin{bmatrix} -1 + 2\,\_t_3 \\ 2 - \_t_3 \\ \_t_3 \end{bmatrix} \quad (2.12)$$

```
> A . x;
```

$$\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \quad (2.13)$$

```
> ReducedRowEchelonForm(B);
```

$$\begin{bmatrix} 1 & 0 & -2 & -1 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (2.14)$$

Zeilenweise Manipulation

```
> B;
```

$$\begin{bmatrix} 1 & 1 & -1 & 1 \\ 2 & 1 & -3 & 0 \\ 1 & 0 & -2 & -1 \end{bmatrix} \tag{3.1}$$

```
> A1 := RowOperation(B, [2,1], -2);
```

$$A1 := \begin{bmatrix} 1 & 1 & -1 & 1 \\ 0 & -1 & -1 & -2 \\ 1 & 0 & -2 & -1 \end{bmatrix} \tag{3.2}$$

```
> A2 := RowOperation(A1, [3,1], -1);
```

$$A2 := \begin{bmatrix} 1 & 1 & -1 & 1 \\ 0 & -1 & -1 & -2 \\ 0 & -1 & -1 & -2 \end{bmatrix} \tag{3.3}$$

```
> A3 := RowOperation(A2, [3,2], -1);
```

$$A3 := \begin{bmatrix} 1 & 1 & -1 & 1 \\ 0 & -1 & -1 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \tag{3.4}$$

```
> A4 := RowOperation(A3, [1,2], 1);
```

$$A4 := \begin{bmatrix} 1 & 0 & -2 & -1 \\ 0 & -1 & -1 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \tag{3.5}$$

```
> A5 := RowOperation(A4, 2, -1);
```

$$A5 := \begin{bmatrix} 1 & 0 & -2 & -1 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \tag{3.6}$$

```
> B
Warning, inserted missing semicolon at end of statement
```

$$\begin{bmatrix} 1 & 1 & -1 & 1 \\ 2 & 1 & -3 & 0 \\ 1 & 0 & -2 & -1 \end{bmatrix} \tag{3.7}$$

Rang und Determinante

```
> Rank(B)
```

Warning, inserted missing semicolon at end of statement

$$2 \tag{4.1}$$

```
> Determinant(A);
```

$$0 \tag{4.2}$$

Normalformen

```
> A; Eigenvalues(A);
```

$$\begin{bmatrix} 1 & 1 & -1 \\ 2 & 1 & -3 \\ 1 & 0 & -2 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 2 \\ -2 \end{bmatrix} \tag{5.1}$$

```
> ew,T := Eigenvectors(A);
```

$$ew, T := \begin{bmatrix} 2 \\ 0 \\ -2 \end{bmatrix}, \begin{bmatrix} 4 & 2 & 0 \\ 5 & -1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \tag{5.2}$$

```
> J := Matrix(ew, shape=diagonal);
```

$$J := \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -2 \end{bmatrix} \tag{5.3}$$

```
> T . J . T^(-1);
```

$$\begin{bmatrix} 1 & 1 & -1 \\ 2 & 1 & -3 \\ 1 & 0 & -2 \end{bmatrix} \tag{5.4}$$

```
> M := << -14 |  -18 |    3 |   11 |  -1 |   16>,
        < -28 |  -36 |   18 |   24 |  -6 |   40>,
        <-134 | -182 |   90 |  126 | -16 |  198>,
        < -12 |  -12 |    2 |   10 |  -2 |    8>,
        < 190 |  254 | -126 | -178 |  24 | -278>,
        <  46 |   62 |  -32 |  -46 |   4 |  -66>>;
```

(5.5)

$$M := \begin{bmatrix} -14 & -18 & 3 & 11 & -1 & 16 \\ -28 & -36 & 18 & 24 & -6 & 40 \\ -134 & -182 & 90 & 126 & -16 & 198 \\ -12 & -12 & 2 & 10 & -2 & 8 \\ 190 & 254 & -126 & -178 & 24 & -278 \\ 46 & 62 & -32 & -46 & 4 & -66 \end{bmatrix} \tag{5.5}$$

```
> J, T := JordanForm(M, output = ['J', 'Q']);
```

$$J, T := \begin{bmatrix} -4 & 0 & 0 & 0 & 0 & 0 \\ 0 & -2\,I & 0 & 0 & 0 & 0 \\ 0 & 0 & 2\,I & 0 & 0 & 0 \\ 0 & 0 & 0 & 4 & 1 & 0 \\ 0 & 0 & 0 & 0 & 4 & 1 \\ 0 & 0 & 0 & 0 & 0 & 4 \end{bmatrix}, \tag{5.6}$$

$$\begin{bmatrix} 6 & -10-24\,I & -10+24\,I & -72 & 46 & 15 \\ 3 & -7+17\,I & -7-17\,I & 144 & -128 & 11 \\ 0 & \frac{41}{2}-\frac{3}{2}\,I & \frac{41}{2}+\frac{3}{2}\,I & 0 & 36 & -41 \\ 6 & -17-7\,I & -17+7\,I & 0 & -72 & 28 \\ 0 & -\frac{7}{2}+\frac{17}{2}\,I & -\frac{7}{2}-\frac{17}{2}\,I & -144 & 128 & 7 \\ 3 & -12+5\,I & -12-5\,I & 72 & -46 & 21 \end{bmatrix}$$

```
> T . J . T^(-1) - M;
```

$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \tag{5.7}$$

Andere Operationen mit Matrizen

```
> restart:
> with(LinearAlgebra):
```

```
> v := Vector(3, symbol = x, orientation = column);
```

$$v := \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \tag{6.1}$$

```
> w := Vector(3, symbol=y, orientation = column);
```

$$w := \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \tag{6.2}$$

```
> w[1];
```

$$y_1 \tag{6.3}$$

```
> v . w;
```

$$\overline{x_1}\, y_1 + \overline{x_2}\, y_2 + \overline{x_3}\, y_3 \tag{6.4}$$

```
> v . w assuming real;
```

$$x_1 y_1 + x_2 y_2 + x_3 y_3 \tag{6.5}$$

```
> CrossProduct(v, w);
```

$$\begin{bmatrix} x_2 y_3 - x_3 y_2 \\ -x_1 y_3 + x_3 y_1 \\ x_1 y_2 - x_2 y_1 \end{bmatrix} \tag{6.6}$$

```
> VectorNorm(v);
```

$$\max(|x_1|, |x_2|, |x_3|) \tag{6.7}$$

```
> VectorNorm(v, 2);
```

$$\sqrt{|x_1|^2 + |x_2|^2 + |x_3|^2} \tag{6.8}$$

```
> with(plots):
> A := <<3, 1, 2>|<5, 2, 1>>;
```

$$A := \begin{bmatrix} 3 & 5 \\ 1 & 2 \\ 2 & 1 \end{bmatrix} \tag{6.9}$$

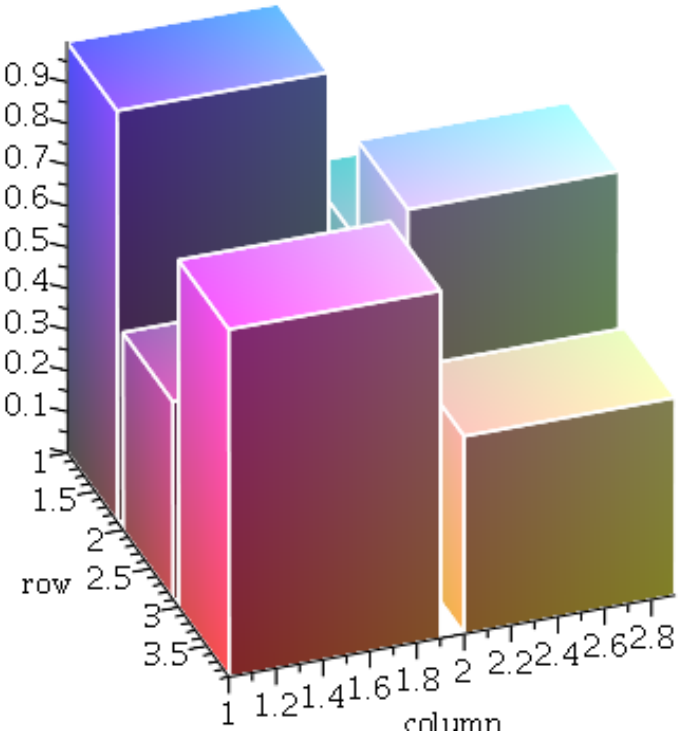
```
> map( x -> x^2, A);
```

$$\begin{bmatrix} 9 & 25 \\ 1 & 4 \\ 4 & 1 \end{bmatrix} \tag{6.10}$$

```
> B:=map( x -> sin(x/2), A);
```

$$B := \begin{bmatrix} \sin\left(\frac{3}{2}\right) & \sin\left(\frac{5}{2}\right) \\ \sin\left(\frac{1}{2}\right) & \sin(1) \\ \sin(1) & \sin\left(\frac{1}{2}\right) \end{bmatrix} \quad \textbf{(6.11)}$$

```
> matrixplot(evalf(B), heights = histogram,gap=0.1,axes=frame,
  orientation=[-20,60]);
```




```
>
```