

# Computergestuetzte Mathematik zur Analysis

## Lektion 11 (9. Januar)

[> restart:

### ▼ Implizite Funktionen

$$\begin{aligned} > \text{g} := \text{solve}(F(x, y), y); \\ & \qquad \qquad \qquad g := \text{RootOf}(F(x, -Z)) \end{aligned} \tag{1.1}$$

$$\begin{aligned} > \text{diff}(g, x); \\ & \qquad \qquad \qquad - \frac{D_1(F)(x, \text{RootOf}(F(x, -Z)))}{D_2(F)(x, \text{RootOf}(F(x, -Z)))} \end{aligned} \tag{1.2}$$

$$\begin{aligned} > \text{diff}(g, x\$2); \\ & - \frac{1}{D_2(F)(x, \text{RootOf}(F(x, -Z)))} \left( D_{1,1}(F)(x, \text{RootOf}(F(x, -Z))) \right. \\ & \quad \left. - \frac{D_{1,2}(F)(x, \text{RootOf}(F(x, -Z))) D_1(F)(x, \text{RootOf}(F(x, -Z)))}{D_2(F)(x, \text{RootOf}(F(x, -Z)))} \right) \\ & + \frac{1}{D_2(F)(x, \text{RootOf}(F(x, -Z)))^2} \left( D_1(F)(x, \text{RootOf}(F(x, -Z))) \left( D_{1,2}(F)(x, \right. \right. \\ & \quad \left. \left. \text{RootOf}(F(x, -Z))) \right. \right. \\ & \quad \left. \left. - \frac{D_{2,2}(F)(x, \text{RootOf}(F(x, -Z))) D_1(F)(x, \text{RootOf}(F(x, -Z)))}{D_2(F)(x, \text{RootOf}(F(x, -Z)))} \right) \right) \end{aligned} \tag{1.3}$$

$$\begin{aligned} > \text{alias}(\alpha = g); \\ & \qquad \qquad \qquad \alpha \end{aligned} \tag{1.4}$$

$$\begin{aligned} > \text{diff}(\alpha, x); \\ & \qquad \qquad \qquad - \frac{D_1(F)(x, \alpha)}{D_2(F)(x, \alpha)} \end{aligned} \tag{1.5}$$

$$\begin{aligned} > \text{normal}(\text{diff}(\alpha, x\$2)); \\ & - \frac{1}{D_2(F)(x, \alpha)^3} \left( D_{1,1}(F)(x, \alpha) D_2(F)(x, \alpha)^2 - 2 D_2(F)(x, \alpha) D_{1,2}(F)(x, \right. \\ & \quad \left. \alpha) D_1(F)(x, \alpha) + D_{2,2}(F)(x, \alpha) D_1(F)(x, \alpha)^2 \right) \end{aligned} \tag{1.6}$$

[Das gleiche zu Fuss:

```
> diff(F(x, y(x)), x);
```

$$D_1(F)(x, y(x)) + D_2(F)(x, y(x)) \left( \frac{d}{dx} y(x) \right) \quad (1.7)$$

```
> isolate((1.7)=0, diff(y(x),x)); #Auflösen nach d/dx y(x)
```

$$\frac{d}{dx} y(x) = - \frac{D_1(F)(x, y(x))}{D_2(F)(x, y(x))} \quad (1.8)$$

```
> diff(F(x,y(x)),x$2);
```

$$D_{1,1}(F)(x, y(x)) + D_{1,2}(F)(x, y(x)) \left( \frac{d}{dx} y(x) \right) + \left( D_{1,2}(F)(x, y(x)) + D_{2,2}(F)(x, y(x)) \left( \frac{d}{dx} y(x) \right) \right) \left( \frac{d}{dx} y(x) \right) + D_2(F)(x, y(x)) \left( \frac{d^2}{dx^2} y(x) \right) \quad (1.9)$$

```
> isolate(=0,diff(y(x),x$2));
```

$$\frac{d^2}{dx^2} y(x) = \frac{1}{D_2(F)(x, y(x))} \left( -D_{1,1}(F)(x, y(x)) - D_{1,2}(F)(x, y(x)) \left( \frac{d}{dx} y(x) \right) - \left( D_{1,2}(F)(x, y(x)) + D_{2,2}(F)(x, y(x)) \left( \frac{d}{dx} y(x) \right) \right) \left( \frac{d}{dx} y(x) \right) \right) \quad (1.10)$$

```
> normal(algsubs((1.8),rhs((1.10)))); #Ersetze d/dx y(x) (1.8) in der RHS von (1.10)
```

$$- \frac{1}{D_2(F)(x, y(x))^3} \left( -2 D_{1,2}(F)(x, y(x)) D_1(F)(x, y(x)) D_2(F)(x, y(x)) + D_{2,2}(F)(x, y(x)) D_1(F)(x, y(x))^2 + D_{1,1}(F)(x, y(x)) D_2(F)(x, y(x))^2 \right) \quad (1.11)$$

## Taylor-Entwicklung in mehreren Veraenderlichen

```
> f := (1-y^2)*exp(-x^2-y);
```

$$f := (1 - y^2) e^{-x^2 - y} \quad (2.1)$$

```
> mtaylor(f, [x=0, y=0], 4);
```

$$1 - y - x^2 - \frac{1}{2} y^2 + yx^2 + \frac{5}{6} y^3 \quad (2.2)$$

```
> for n from 1 to 9 do;
>   p[n] := mtaylor(f, [x=0, y=0], n);
> od;
> for n from 1 to 6 do;
>   'n' = n, 'p' = p[n];
> od;
```

$$n = 1, p = 1$$

$$n = 2, p = 1 - y$$

$$n = 3, p = 1 - y - x^2 - \frac{1}{2} y^2$$

$$n=4, p=1-y-x^2-\frac{1}{2}y^2+yx^2+\frac{5}{6}y^3$$

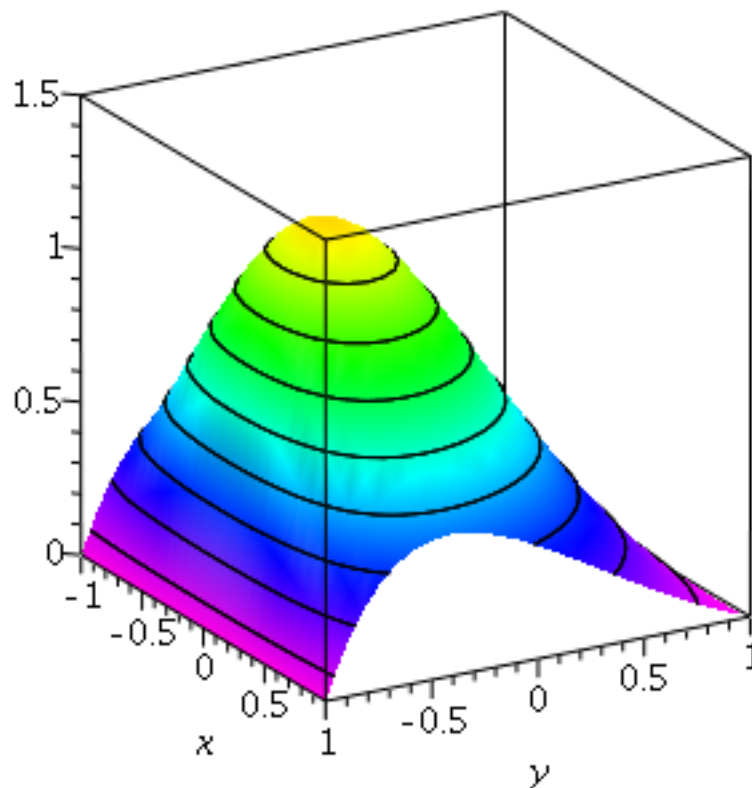
$$n=5, p=1-y-x^2-\frac{1}{2}y^2+yx^2+\frac{5}{6}y^3+\frac{1}{2}x^4+\frac{1}{2}x^2y^2-\frac{11}{24}y^4$$

$$n=6, p=1-y-x^2-\frac{1}{2}y^2+yx^2+\frac{5}{6}y^3+\frac{1}{2}x^4+\frac{1}{2}x^2y^2-\frac{11}{24}y^4-\frac{1}{2}x^4y$$

$$-\frac{5}{6}x^2y^3+\frac{19}{120}y^5$$

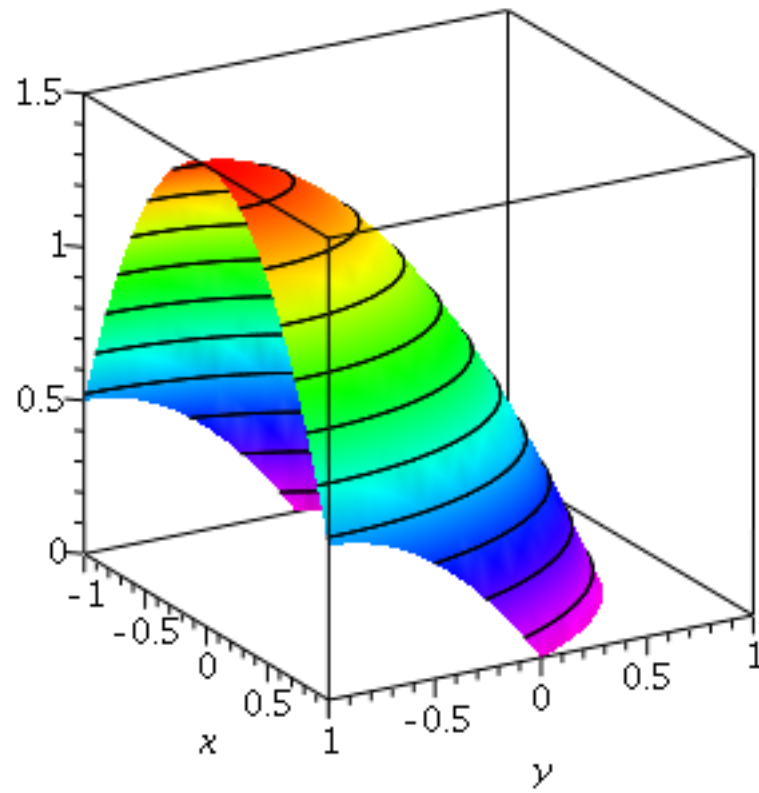
```
> optionen := x = -1 .. 1, y = -1 .. 1, view = 0 .. 1.5,
orientation = [-30, 70], axes = boxed, style = patchcontour,
shading = zhue;
optionen:= x = -1..1, y = -1..1, view = 0..1.5, orientation = [-30, 70], axes
= boxed, style = patchcontour, shading = zhue
> plot3d(f, optionen, title = "f");
```

f



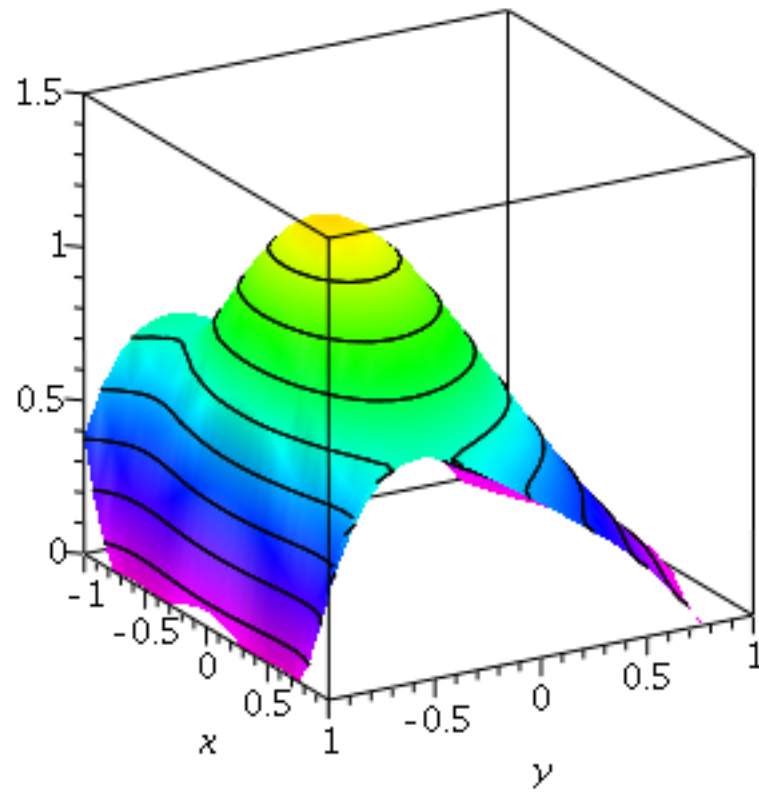
```
> plot3d(p[3], optionen, title = "p[3]");
```

p[3]



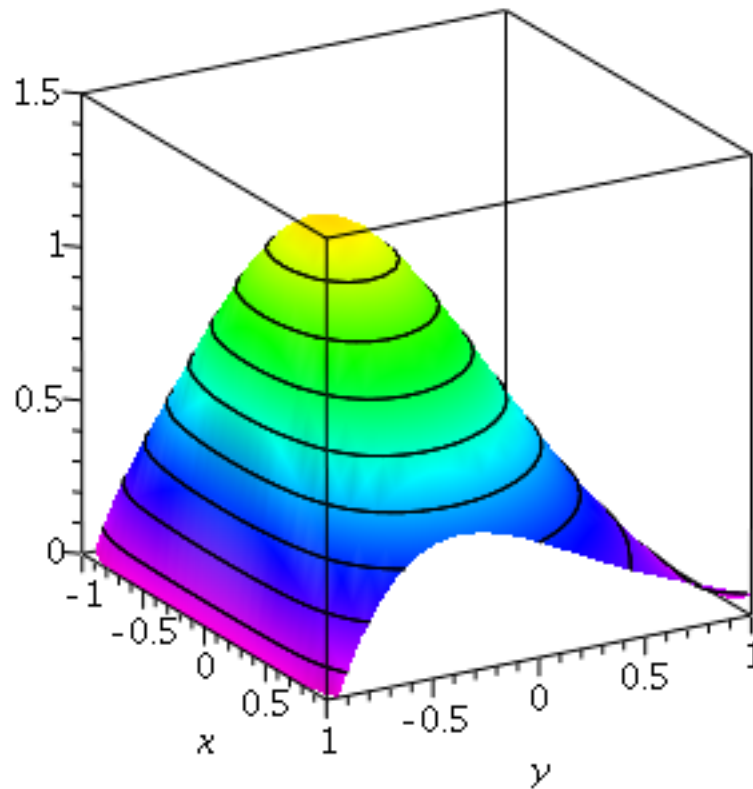
```
> plot3d(p[6], optionen, title = "p[6]");
```

p[6]



```
> plot3d(p[9], optionen, title = "p[9]");
```

p[9]



## ▼ Noch etwas Datenstrukturen

```
> liste1 := [28, 2^6, 0, -3];  
liste1 := [28, 64, 0, -3] (3.1)
```

```
> is_pos := t -> evalb(t > 0);  
is_pos := t -> evalb(0 < t) (3.2)
```

```
> map(is_pos, liste1);  
[true, true, false, false] (3.3)
```

```
> select(is_pos, liste1);  
[28, 64] (3.4)
```

```
> f := cos(y^2);  
f := cos(y^2) (3.5)
```

```
> has(f, y);  
true (3.6)
```

```
> has(f, y^2);  
true (3.7)
```

```
> has(f, y^3);  
false (3.8)
```

```
> liste := [x^3, exp(-4), x^2 + 15];  
liste := [x^3, e^-4, x^2 + 15] (3.9)
```

```
> test1 := t -> has(t, x^3);  
test1 := t → has(t, x^3) (3.10)
```

```
> select(test1, liste);  
[x^3] (3.11)
```

```
> test2 := t -> has(t, exp);  
test2 := t → has(t, exp) (3.12)
```

```
> select(test2, liste);  
[e^-4] (3.13)
```

```
> test3 := t -> has(t, 15);  
test3 := t → has(t, 15) (3.14)
```

```
> select(test3, liste);  
[x^2 + 15] (3.15)
```

```
> A := [seq(a[j], j = 1 .. 5)];  
A := [a_1, a_2, a_3, a_4, a_5] (3.16)
```

```
> B := [seq(b[j], j = 1 .. 4)];  
B := [b_1, b_2, b_3, b_4] (3.17)
```

```
> zip(F, A, B);  
[F(a_1, b_1), F(a_2, b_2), F(a_3, b_3), F(a_4, b_4)] (3.18)
```

```
> G := (a,b) -> (a,b);  
G := (a, b) → (a, b) (3.19)
```

```
> zip(G, A, B);  
[a_1, b_1, a_2, b_2, a_3, b_3, a_4, b_4] (3.20)
```

```
> zip(G, 1, B);  
[1, b_1, 1, b_2, 1, b_3, 1, b_4] (3.21)
```